

## Part I: Numerical Fourier analysis of quasi-periodic functions

### I.1 The procedure

$$f(t) \sim Q_f(t; A, \omega)$$

$$\text{DFT}(f) = \text{DFT}(Q_f)$$

### I.2 Error estimation

- *Applying the above procedure, the system to be solved can be written as*

$$g(y + \Delta y) = b + \Delta b.$$

- *The exact frequencies and amplitudes would be obtained if  $\Delta b = 0$ .*
- *A bound for the error is given by*

$$\|\Delta y\| \leq \|Dg(y)^{-1}\| \|\Delta b\|.$$

- *We will bound  $\|Dg(y)^{-1}\|$  and  $\|\Delta b\|$ .*

### I.3 Applications

- *Academic example, to show the procedure and the accuracy of the error estimation*
- *Solar System models:*

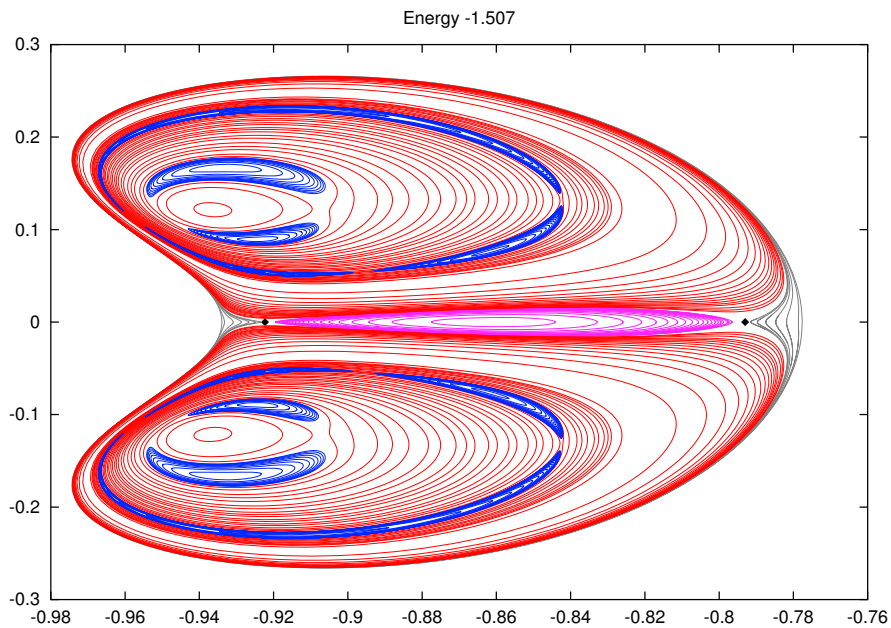
$$\text{SS} = \text{RTBP} + \text{Perturbations}$$

$$\Downarrow \text{ (Fourier analysis)}$$

$$\text{SS} = \text{RTBP} + \text{Perturbations}(\omega_1, \omega_2, \dots)$$

## Part II: The neighborhood of the collinear equilibrium points in the RTBP

Final goal: *To get Poincaré section representations of the flow around  $L_{1,2,3}$ .*



Tools: *Parallel algorithms for the computation of different kinds of families of periodic orbits and invariant tori.*

## I.1 Refined Fourier analysis procedure

Given a **real analytic quasi-periodic function**,  $f(t)$ , at  $N$  equally-spaced points on an interval  $[0, T]$ ,

$$\{f(t_l)\}_{l=0}^{N-1}, \quad t_l = l\frac{T}{N},$$

**the goal** is to compute a trigonometric approximation

$$Q_f(t) = A_0^c + \sum_{l=1}^{N_f} (A_l^c \cos(2\pi\frac{\nu_l}{T}t) + A_l^s \sin(2\pi\frac{\nu_l}{T}t)).$$

The Discrete Fourier Transform (DFT) of  $f$  is defined through

$$f(t_l) = \frac{1}{2}(c_{f,T,N}(0) + c_{f,T,N}(\frac{N}{2}) \cos(\frac{2\pi\frac{N}{2}t_l}{T})) + \sum_{j=1}^{N/2-1} (c_{f,T,N}(j) \cos(\frac{2\pi jt_l}{T}) + s_{f,T,N}(j) \sin(\frac{2\pi jt_l}{T})).$$

where

$$c_{f,T,N}(j) = \frac{2}{N} \sum_{l=0}^{N-1} f(t_l) \cos(2\pi\frac{j}{N}l), \quad j = 0, \dots, \frac{N}{2},$$

$$s_{f,T,N}(j) = \frac{2}{N} \sum_{l=0}^{N-1} f(t_l) \sin(2\pi\frac{j}{N}l), \quad j = 1, \dots, \frac{N}{2} - 1.$$

## Algorithm

1. Set an starting **threshold** for collecting **peaks of the modulus of the DFT** of  $f(t)$ .
2. Find initial **approximations of the frequencies**, starting from the peaks of the DFT greater than the threshold.
3. Find the **amplitudes** of the frequencies found in the previous step ( $\text{DFT}(Q_f) = \text{DFT}(f)$ ).
4. Simultaneously **refine ALL the frequencies and amplitudes** of the current quasi-periodic approximation of  $f$ .
5. Perform a **DFT of the input signal minus the current quasi-periodic approximation** obtained in step 4, **decrease the threshold** and go **back to step 2**.

### Equations of step 3

We ask  $\text{DFT}(Q_f) = \text{DFT}(f)$ , being

$$Q_f(t) = A_0^c + \sum_{l=1}^{N_f} (A_l^c \cos(2\pi \frac{\nu_l}{T} t) + A_l^s \sin(2\pi \frac{\nu_l}{T} t)).$$

The system of equations to be solved is **linear** and  $(1 + 2N_f) \times (1 + 2N_f)$ :

$$\begin{aligned} A_0^c c_{1,T,N}^{n_h}(0) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l,N}^{n_h}(0) + A_l^s \tilde{c}_{\nu_l,N}^{n_h}(0)) &= c_{f,T,N}^{n_h}(0) \\ A_0^c c_{1,T,N}^{n_h}(j) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l,N}^{n_h}(j) + A_l^s \tilde{c}_{\nu_l,N}^{n_h}(j)) &= c_{f,T,N}^{n_h}(j) \\ \sum_{l=1}^{N_f} (A_l^c \bar{s}_{\nu_l,T}^{n_h}(j) + A_l^s \tilde{s}_{\nu_l,T}^{n_h}(j)) &= s_{f,T,N}^{n_h}(j) \end{aligned}$$

where  $j = [\nu_l + 0.5]$ ,  $l = 1 \div N_f$ , and

$$\begin{aligned} c_1^{n_h}(j) &= c_{1,T,N}^{n_h}(j), \\ \bar{c}_{\nu_l,N}^{n_h}(j) &= c_{\cos(\frac{2\pi\nu_l}{T}),T,N}^{n_h}(j), & \bar{s}_{\nu_l,N}^{n_h}(j) &= s_{\cos(\frac{2\pi\nu_l}{T}),T,N}^{n_h}(j), \\ \tilde{c}_{\nu_l,N}^{n_h}(j) &= c_{\sin(\frac{2\pi\nu_l}{T}),T,N}^{n_h}(j), & \tilde{s}_{\nu_l,N}^{n_h}(j) &= s_{\sin(\frac{2\pi\nu_l}{T}),T,N}^{n_h}(j). \end{aligned}$$

## Equations for step 4

The system of equations is a  $(1 + 3N_f) \times (1 + 3N_f)$  **non-linear system** which is solved by **Newton's method**:

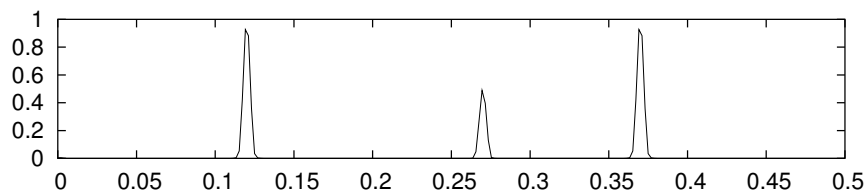
$$\begin{aligned}
 A_0^c c_{1,T,N}^{n_h}(0) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l,N}^{n_h}(0) + A_l^s \tilde{c}_{\nu_l,N}^{n_h}(0)) &= c_{f,T,N}^{n_h}(0) \\
 A_0^c c_{1,T,N}^{n_h}(j_i) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l,N}^{n_h}(j_i) + A_l^s \tilde{c}_{\nu_l,N}^{n_h}(j_i)) &= c_{f,T,N}^{n_h}(j_i) \\
 \sum_{l=1}^{N_f} (A_l^c \bar{s}_{\nu_l,N}^{n_h}(j_i) + A_l^s \tilde{s}_{\nu_l,N}^{n_h}(j_i)) &= s_{f,T,N}^{n_h}(j_i) \\
 A_0^c c s_{1,T,N}^{n_h}(j_i^+) + \sum_{l=1}^{N_f} (A_l^c \bar{c} s_{\nu_l,N}^{n_h}(j_i^+) + A_l^s \tilde{c} s_{\nu_l,N}^{n_h}(j_i^+)) &= c s_{f,T,N}^{n_h}(j_i^+)
 \end{aligned}$$

being  $j_i = [\nu_i + 0.5]$ ,  $j_i^+ \neq j_i$ ,  $|j_i^+ - j_i| = 1$ .

## An example:

$$f(t) = \cos(2\pi 0.23t) - \frac{1}{2} \sin(2\pi 0.27t) + \sin(2\pi 0.37t).$$

- Starting threshold: 0.8  
modulus of the DFT of the input data:



⇒ peaks  $j = 61$ ,  $j = 189$ .

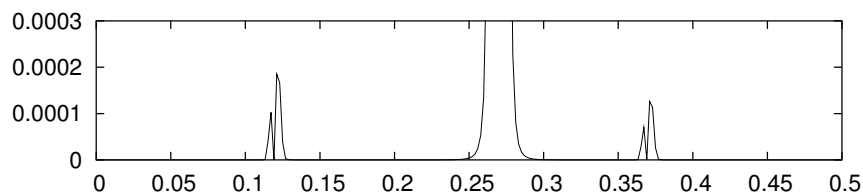
- Approximation of frequencies (Laskar's method):

peak 61 ⇒ frequency 0.11999948789  
peak 189 ⇒ frequency 0.36999965075

- Computation of amplitudes from known frequencies:

Frequency	Cosine amplitude	Sine amplitude
0.119999487888	0.999907666367	-0.000823654552
0.369999650752	0.000561727398	0.999937098420

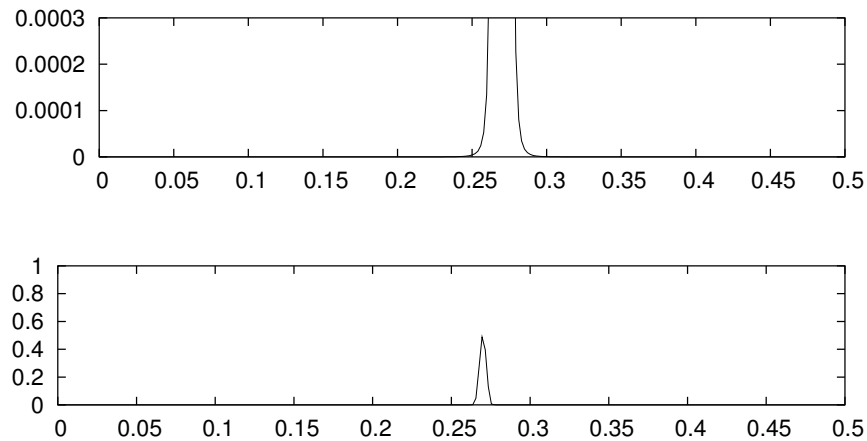
modulus of the DFT of the residual



- Iterative refinement:

Frequency	Cosine amplitude	Sine amplitude
0.120000000003	1.000000000686	0.000000005106
0.369999999995	0.000000006660	1.000000000297

5. modulus of the DFT of input signal minus step 4:



New threshold: 0.2

2. Approximation of frequencies (Laskar's method):

peak 138  $\Rightarrow$  frequency 0.2699999999988849

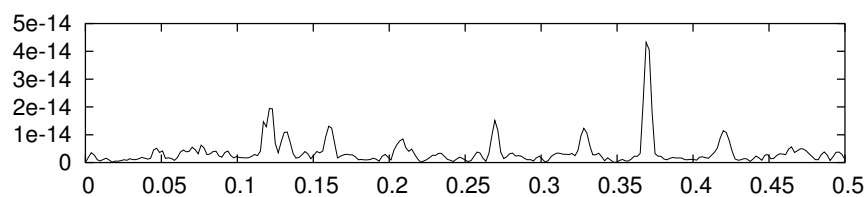
3. Amplitudes from known frequencies:

Frequency	Cosine amplitude	Sine amplitude
0.120000000003	1.000000000586	0.000000005245
0.369999999995	0.000000007480	0.999999999164
0.269999999999	-0.000000000897	-0.499999999946

4. Iterative refinement:

Frequency	Cosine amplitude	Sine amplitude
0.1200000000000000	0.999999999999999	-0.0000000000000008
0.3700000000000000	-0.0000000000000001	1.0000000000000000
0.2700000000000000	0.0000000000000000	-0.5000000000000000

modulus of the DFT of the residual:





## I.2 Error estimation

We assume

- $f$  is **real analytic** and **quasi-periodic**,

$$f(t) = A_0^c + \sum_{\substack{k \in \mathbb{Z}^m \\ k\omega > 0}} (A_k^c \cos(2\pi k\omega t) + A_k^s \sin(2\pi k\omega t)),$$

and its Fourier coefficients  $a_k$  satisfy the **Cauchy estimates**

$$\sqrt{(A_k^c)^2 + (A_k^s)^2} \leq C e^{-\delta|k|} \quad \forall k \in \mathbb{Z}^m.$$

- The frequency vector  $\omega = (\omega_1, \dots, \omega_m)$  satisfies a **Diophantine condition**

$$|k\omega| \geq \frac{D}{|k|^\tau},$$

with  $D, \tau > 0$ .

- We determine the frequencies  $\{\nu_l\}_{l=1}^{N_f}$  of order  $\leq r_0 - 1$  ( $\nu_l \approx Tk\omega$ ,  $1 \leq |k| \leq r_0 - 1$ ) and the corresponding amplitudes  $\{A_l^c\}_{l=0}^{N_f}$ ,  $\{A_l^s\}_{l=1}^{N_f}$ .

## Strategy

Let us denote,

$$f_{r_0}(t) = A_0^c + \sum_{\substack{|k| \leq r_0 - 1 \\ k\omega > 0}} (A_k^c \cos(2\pi k\omega t) + A_k^s \sin(2\pi k\omega t)).$$

The system of equations used for simultaneous improvement of frequencies and amplitudes can be written as

$$\begin{aligned} A_0^c + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l, N}^{n_h}(0) + A_l^s \tilde{c}_{\nu_l, N}^{n_h}(0)) &= c_{f_{r_0}, T, N}^{n_h}(0) + c_{f-f_{r_0}, T, N}^{n_h}(0) \\ A_0^c c_1^{n_h}(j_i) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l, N}^{n_h}(j_i) + A_l^s \tilde{c}_{\nu_l, N}^{n_h}(j_i)) &= c_{f_{r_0}, T, N}^{n_h}(j_i) + c_{f-f_{r_0}, T, N}^{n_h}(j_i) \\ \sum_{l=1}^{N_f} (A_l^c \bar{s}_{\nu_l, N}^{n_h}(j_i) + A_l^s \tilde{s}_{\nu_l, N}^{n_h}(j_i)) &= s_{f_{r_0}, T, N}^{n_h}(j_i) + s_{f-f_{r_0}, T, N}^{n_h}(j_i) \\ \underbrace{A_0^c c_1^{n_h}(j_i^+) + \sum_{l=1}^{N_f} (A_l^c \bar{c}_{\nu_l, N}^{n_h}(j_i^+) + A_l^s \tilde{c}_{\nu_l, N}^{n_h}(j_i^+))}_{g(y + \Delta y)} &= \underbrace{c_{f_{r_0}, T, N}^{n_h}(j_i^+)}_b + \underbrace{c_{f-f_{r_0}, T, N}^{n_h}(j_i^+)}_{\Delta b}. \end{aligned}$$

We would get the **exact** frequencies and amplitudes **if**  $\Delta b = 0$ .

The **error in frequencies and amplitudes** is given, in the first order approximation, by

$$\|\Delta y\|_\infty \lesssim \|Dg(y)^{-1}\|_\infty \|\Delta b\|_\infty.$$

We will obtain **bounds for**  $\|Dg(y)^{-1}\|_\infty$  **and**  $\|\Delta b\|_\infty$ .

## Bound for $\|Dg(y)^{-1}\|_\infty$ Preliminaries

We can write

$$Dg(y) =: M = \begin{pmatrix} 2 & B_{0,1} & \dots & B_{0,N_f} \\ 0 & B_{1,1} & \dots & B_{1,N_f} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & B_{N_f,1} & \dots & B_{N_f,N_f} \end{pmatrix}.$$

We **split**  $M = M_D + M_O$ ,

$$M = \begin{pmatrix} 2 & 0 & \dots & 0 \\ 0 & B_{1,1} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & B_{N_f,N_f} \end{pmatrix} + \begin{pmatrix} 0 & B_{0,1} & \dots & B_{0,N_f} \\ 0 & 0 & \dots & B_{1,N_f} \\ 0 & \vdots & \ddots & \vdots \\ 0 & B_{N_f,1} & \dots & 0 \end{pmatrix}.$$

The idea is to obtain **bounds for**  $\|M_D^{-1}\|$ ,  $\|M_O\|$  and use

$$\|(M_D + M_O)^{-1}\| \leq \frac{\|M_D^{-1}\|}{1 - \|M_D^{-1}\|\|M_O\|}.$$

The components  $B_{i,l}$  of  $M$  ( $i \neq 0$ ) have the following general aspect

$$\begin{pmatrix} A_l^c \partial \bar{c}_{\nu_l, N}^{n_h}(j_i) + A_l^s \partial \tilde{c}_{\nu_l, N}^{n_h}(j_i) & \bar{c}_{\nu_l, N}^{n_h}(j_i) & \tilde{c}_{\nu_l, N}^{n_h}(j_i) \\ A_l^c \partial \bar{s}_{\nu_l, N}^{n_h}(j_i) + A_l^s \partial \tilde{s}_{\nu_l, N}^{n_h}(j_i) & \bar{s}_{\nu_l, N}^{n_h}(j_i) & \tilde{s}_{\nu_l, N}^{n_h}(j_i) \\ A_l^c \partial \bar{c}s_{\nu_l, N}^{n_h}(j_i^+) + A_l^s \partial \tilde{c}s_{\nu_l, N}^{n_h}(j_i^+) & \bar{c}s_{\nu_l, N}^{n_h}(j_i^+) & \tilde{c}s_{\nu_l, N}^{n_h}(j_i^+) \end{pmatrix}.$$

## First simplification: $M \rightarrow \mathcal{M}$

The first simplification consists in the use of the **Truncated Continuous Fourier Transform** ( $\mathcal{C}, \mathcal{S}$ ),

$$\frac{1}{T} \int_0^T H_T^{n_h}(t) f(t) e^{-i2\pi \frac{j}{T} t} dt =: \frac{1}{2} (\mathcal{C}_{f,T}^{n_h}(j) + i\mathcal{S}_{f,T}^{n_h}(j))$$

instead of the **DFT** ( $c, s$ ).

We define  $\widetilde{\mathcal{C}\mathcal{S}}_\nu^{n_h}(j)$  as in the discrete case.

In this way,

$$\begin{aligned} M &= M_D + M_O \\ &\quad \downarrow \text{(substitute DFT by TCFT)} \\ \mathcal{M} &= \mathcal{M}_D + \mathcal{M}_O \end{aligned}$$

**Remark 1:** The difference between  $\widetilde{c\overline{s}}$  and  $\widetilde{\mathcal{C}\mathcal{S}}$  can be bounded from a **discrete** version of **Poisson's summation formula**:

$$c_{f,T,N}^{n_h}(j) = \sum_{l=-\infty}^{\infty} c_{f,T}^{n_h}\left(\frac{j + lN}{T}\right), \dots$$

**Remark 2:** Explicit formulae for the components of  $\mathcal{M}$  can be obtained.

## Formulae for the components of $\mathcal{M}$

The components of the matrix  $\mathcal{M}$  are given by

$$\begin{aligned} \bar{c}_\nu^{n_h}(j) &= K_{n_h} \left( \frac{\sin(2\pi(\nu - j))}{\psi_{n_h}(\nu - j)} + \frac{\sin(2\pi(-\nu - j))}{\psi_{n_h}(-\nu - j)} \right), \\ \vdots & \\ \partial \bar{c}_\nu^{n_h}(j) &= K_{n_h} \left( \frac{h_r(\nu - j)}{\psi_{n_h}(\nu - j)} - \frac{h_r(-\nu - j)}{\psi_{n_h}(-\nu - j)} \right), \\ \vdots & \end{aligned}$$

where

$$\begin{aligned} K_{n_h} &= \frac{(-1)^{n_h} (n_h!)^2}{2\pi} \\ \psi_{n_h}(x) &= \prod_{l=-n_h}^{n_h} (x + l) \\ h_r(x) &= 2\pi \cos(2\pi x) - r_{n_h}(x) \sin(2\pi x), \\ h_i(x) &= 2\pi \sin(2\pi x) - r_{n_h}(x) (1 - \cos(2\pi x)), \\ r_{n_h}(x) &= \sum_{l=-n_h}^{n_h} \frac{1}{x + l} = \frac{\psi'_{n_h}(x)}{\psi_{n_h}(x)}. \end{aligned}$$

## Second simplification: $\mathcal{M} \rightarrow \mathfrak{M}$

The second simplification consist in **eliminating the second summands** of the expressions of the components of  $\mathcal{M}$  as given in the previous lemma.

In this way,

$$\begin{aligned}\mathcal{M} &= \mathcal{M}_D + \mathcal{M}_O \\ &\quad \downarrow \text{(remove the second summands)} \\ \mathfrak{M} &= \mathfrak{M}_D + \mathfrak{M}_O\end{aligned}$$

**Remark 1:** The difference between the components of  $\mathcal{M}$  and  $\mathfrak{M}$  ( $\widetilde{\mathcal{CS}}$  and  $\widetilde{\mathfrak{CS}}$ ) can be bounded.

**Remark 2:** the expression for  $\widetilde{\mathfrak{CS}}$  only depends on the difference  $\nu - j$ .

## Bound for $\|\mathfrak{M}_D^{-1}\|_\infty$

Since  $\mathfrak{M}_D$  is diagonal, to compute  $\mathfrak{M}_D^{-1}$  we only need to invert its diagonal blocks  $\mathfrak{B}_{i,i}$

$$\begin{pmatrix} A_i^c \partial \bar{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) + A_i^s \partial \tilde{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) & \bar{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) & \tilde{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) \\ A_i^c \partial \bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) + A_i^s \partial \tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) & \bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) & \tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) \\ A_i^c \partial \bar{\mathbf{c}}\bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) + A_i^s \partial \tilde{\mathbf{c}}\tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) & \bar{\mathbf{c}}\bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) & \tilde{\mathbf{c}}\tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) \end{pmatrix}.$$

For that, we first show that, if  $(A_i^c, A_i^s) \neq (0, 0)$ ,  $\mathfrak{B}_{i,i}$  is invertible either setting  $\mathbf{c}\mathbf{s} = \mathbf{c}$  or  $\mathbf{c}\mathbf{s} = \mathbf{s}$ .

The actual bounds of  $\mathfrak{B}_{i,i}$  are computed **numerically** for each  $n_h$ , by first minimizing w.r.t.  $\mathbf{c}\mathbf{s} = \mathbf{c}, \mathbf{s}$  and maximizing w.r.t.  $\theta \in [0, 2\pi]$ ,  $|\nu - j| \leq 1/2$  the supremum norm of

$$\begin{pmatrix} \partial \bar{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) \cos \theta + \partial \tilde{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) \sin \theta & \bar{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) & \tilde{\mathbf{c}}_{\nu_i, N}^{n_h}(j_i) \\ \partial \bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) \cos \theta + \partial \tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) \sin \theta & \bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) & \tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i) \\ \partial \bar{\mathbf{c}}\bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) \cos \theta + \partial \tilde{\mathbf{c}}\tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) \sin \theta & \bar{\mathbf{c}}\bar{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) & \tilde{\mathbf{c}}\tilde{\mathbf{s}}_{\nu_i, N}^{n_h}(j_i^+) \end{pmatrix}^{-1}.$$

We call  $G_{n_h}$  the obtained quantity. Some values are

$n_h$	0	1	2	3
$G_{n_h}$	4.84	8.83	13.3	17.7

In this way, we get

$$\|(\mathfrak{M}_D)^{-1}\| \leq \max(A_{min}^{-1}, 1)G_{n_h},$$

being

$$\begin{aligned} A_i &= ((A_i^c)^2 + (A_i^s)^2)^{1/2} \\ A_{min} &= \min_{i=1 \div N_f} \{A_1, \dots, A_{N_f}\} \end{aligned}$$

## Bounds for $\|M^{-1}\|_\infty$

The computation of the bound for  $\|Dg(y)^{-1}\|$  is completed by following the following scheme:

$$\|\mathfrak{M}_D^{-1}\| \leq \max(A_{min}^{-1}, 1)G_{n_h}$$

↓

$$\|\mathcal{M}_D^{-1}\| \leq \frac{\|\mathfrak{M}_D^{-1}\|}{1 - \|\mathfrak{M}_D^{-1}\| \|\mathfrak{M}_D - \mathcal{M}_D\|}$$

↓

$$\|M_D^{-1}\| \leq \frac{\|\mathcal{M}_D^{-1}\|}{1 - \|\mathcal{M}_D^{-1}\| \|\mathcal{M}_D - M_D\|}$$

$$\Downarrow \|M_O\| \leq \|\mathfrak{M}_O\| + \|\mathfrak{M}_O - \mathcal{M}_O\| + \|\mathcal{M}_O - M_O\|$$

$$\|M^{-1}\| \leq \frac{\|M_D^{-1}\|}{1 - \|M_D^{-1}\| \|M_O\|}$$

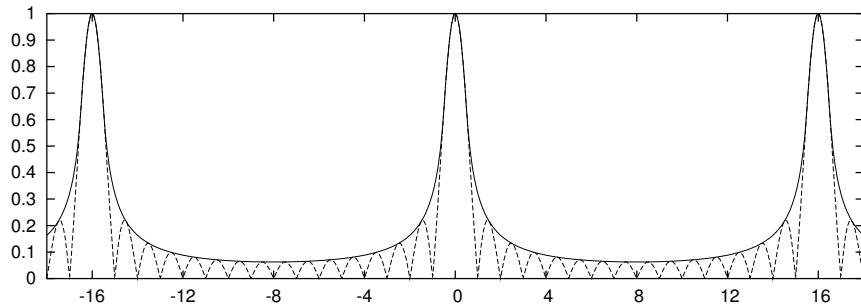


## Bound for $\|\Delta b\|_\infty$

We have

$$\|\Delta b\| \leq 2C \max_{j \in J} \sum_{|k|=r_0}^{\infty} e^{-\delta|k|} |\tilde{h}_N^{n_h}(Tk\omega - j)|,$$

where  $|\tilde{h}_N^{n_h}|$  is the envelope displayed below ( $N = 16$ ,  $n_h = 0$ ).



The **Diophantine condition** gives a **lower bound** for  $|Tk\omega - j|$ :

$$|Tk\omega - j| \geq \frac{TD}{(|k| + |k_j|)^\tau} - 1.$$

For  $|k|$  **small**,  $|\tilde{h}_N^{n_h}(Tk\omega - j)| \ll 1$ .

After some order  $r_*$ ,  $|\tilde{h}_N^{n_h}(Tk\omega - j)|$  may approach 1.

Therefore,

$$\|\Delta b\| \leq 2C \left( \max_{j \in J} \sum_{\substack{|k|=r_0 \\ |k|=r_0}}^{r_*-1} e^{-\delta|k|} |\tilde{h}_N^{n_h}(Tk\omega - j)| + \max_{j \in J} \sum_{|k|=r_*}^{\infty} e^{-\delta|k|} \right),$$

where:

- The first term is bounded by **replacing the DFT by the TCFT**. This introduces an additional error term due to this approximation.
- All the sums are reduced to **sums of the form**  $\sum_j j^\alpha e^{-\delta j}$ , which are bounded by **incomplete Gamma functions**.

## Final theorem

Under the stated hypothesis, the error in frequencies and amplitudes can be bounded as

$$\|\Delta y\| \lesssim \|M^{-1}\| \|\Delta b\|,$$

where

$$\|M^{-1}\| \leq \frac{\|M_D^{-1}\|}{1 - \|M_D^{-1}\| \|M_O\|}$$

and

$$\begin{aligned} \|M_O\| \leq & \frac{(n_h!)^2}{\pi} \left( \frac{\sqrt{2} \left( \sum_{l=1}^{N_f} A_l \right) \left( \pi + \ln \left( \frac{TD}{(2r_0-2)^\tau} - 1 + n_h \right) - \ln \left( \frac{TD}{(2r_0-2)^\tau} - 2 - n_h \right) \right) + 2N_f}{\left( \frac{TD}{(2r_0-2)^\tau} - 1 - n_h \right)^{1+2n_h}} \right. \\ & + \frac{\sqrt{2} \left( \sum_{l=1}^{N_f} A_l \right) \left( \pi + \ln([\nu_{min}] + n_h) - \ln([\nu_{min}] - 1 - n_h) \right) + 2N_f}{([\nu_{min}] - n_h)^{1+2n_h}} \\ & \left. + \frac{4 \left( \sqrt{2} \left( \sum_{l=1}^{N_f} A_l \right) \left( \pi + \ln(N - \Omega_0 + n_h) - \ln(N - \Omega_0 - 1 - n_h) \right) + 2N_f \right) \left( 1 + \frac{1}{2n_h} \right)}{(N - \Omega_0 - n_h)^{1+2n_h}} \right) \end{aligned}$$

and

$$\|M_D^{-1}\| \leq \frac{\|\mathcal{M}_D^{-1}\|}{1 - \|\mathcal{M}_D^{-1}\| \varepsilon_1}, \quad \|\mathcal{M}_D^{-1}\| \leq \frac{\|\mathfrak{M}_D^{-1}\|}{1 - \|\mathfrak{M}_D^{-1}\| \varepsilon_2}, \quad \|\mathfrak{M}_D^{-1}\| \leq \frac{G_{n_h}}{\min(1, A_{min})},$$

being

$$\begin{aligned} \varepsilon_1 &= \frac{4(n_h!)^2 \left( \sqrt{2} A_{max} \left( \pi + \ln(N - \Omega_0 + n_h) - \ln(N - \Omega_0 - 1 - n_h) \right) + 2 \right) \left( 1 + \frac{1}{2n_h} \right)}{\pi (N - \Omega_0 - n_h)^{1+2n_h}}, \\ \varepsilon_2 &= \frac{(n_h!)^2 \left( \sqrt{2} A_{max} \left( \pi + \ln(2[\nu_{min}] + n_h) - \ln(2[\nu_{min}] - n_h - 1) \right) + 2 \right)}{\pi (2[\nu_{min}] - n_h)^{1+2n_h}}, \\ \Omega_0 &= T(2r_0 - 2) \|\omega\|_\infty + 1, \end{aligned}$$

## Error estimates: Final theorem (cont.)

As for  $\|\Delta b\|$ ,

$$\begin{aligned} \|\Delta b\| \leq & \frac{2^{m+1}C}{(m-1)!} \left( \right. \\ & \chi_{\{r_* > r_0\}} \frac{(n_h!)^2 e^{\delta(r_0-1)} \sum_{l=0}^{m-1} \binom{m-1}{l} \left(\frac{m}{2} - r_0 + 1\right)^{m-1-l} G_f(2r_0-1, r_0+r_*-2, l+\tau(1+2n_h), \delta)}{E_* \pi (TD)^{1+2n_h}} \\ & + \chi_{\{r_* > r_0\}} \frac{2(n_h!)^2 e^{\delta \frac{m}{2}} \left(1 + \frac{1}{2n_h}\right) G_f\left(r_0 + \frac{m}{2}, r_* - 1 + \frac{m}{2}, m-1, \delta\right)}{\pi (N - \Omega - n_h)^{1+2n_h}} \\ & \left. + e^{\delta \frac{m}{2}} G_\infty\left(r_* + \frac{m}{2}, m-1, \delta\right), \right) \end{aligned}$$

where

$$\begin{aligned} \Omega &= T(r_* + r_0 - 2) \|\omega\|_\infty + 1 \\ r_* &= \max\left(r_0, \min\left(\left[\left(\frac{TD}{\max\left(\left(\frac{(n_h!)^2}{\pi}\right)^{\frac{1}{1+2n_h}} + 1 + n_h, 2(1+n_h)\right)}\right)^{\frac{1}{\tau}} - r_0 + 2\right], \right. \right. \\ & \quad \left. \left. \left[\frac{N-1-n_h}{T\|\omega\|_\infty} - r_0 + 1\right]\right)\right) \\ E_* &= \frac{(z_* - 1 - n_h)^{1+2n_h}}{z_*^{1+2n_h}}, \\ z_* &= \frac{TD}{(r_* + r_0 - 2)^\tau}, \end{aligned}$$

In the above formulas,  $\chi_{\{condition\}}$  equals 1 if *condition* is true and 0 otherwise.

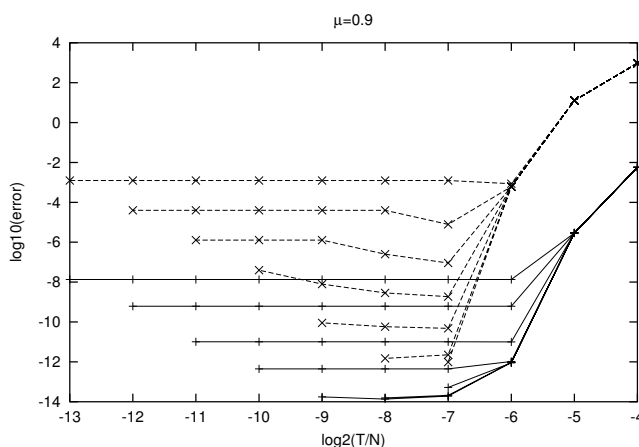
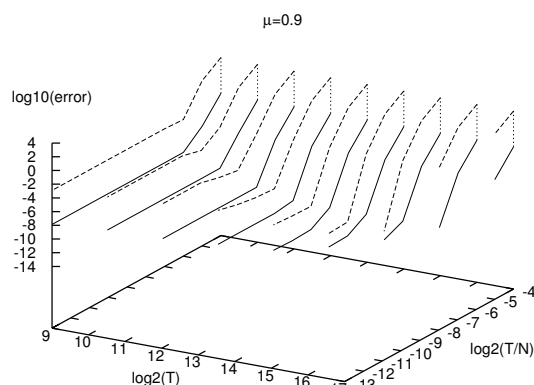
## I.3 Applications “Academic” example

We consider the **quasi-periodic function**

$$f_{0.9}(t) = \frac{\sin(2\pi\omega_1 t + \varphi_1)}{1 - 0.9 \cos(2\pi\omega_1 t + \varphi_1)} \cdot \frac{\sin(2\pi\omega_2 t + \varphi_2)}{1 - 0.9 \cos(2\pi\omega_2 t + \varphi_2)}.$$

Explicit formulae for frequencies and amplitudes can be obtained, as well as the **Cauchy estimates** and the **Diophantine condition**.

We have performed **Fourier analysis** of this function for **several**  $T, N$ .

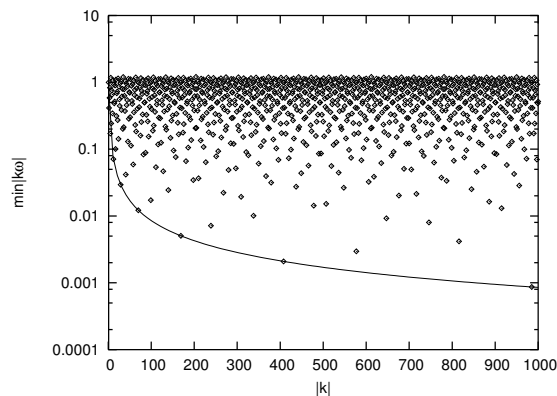


Solid line: actual error. Dashed line: estimated error.

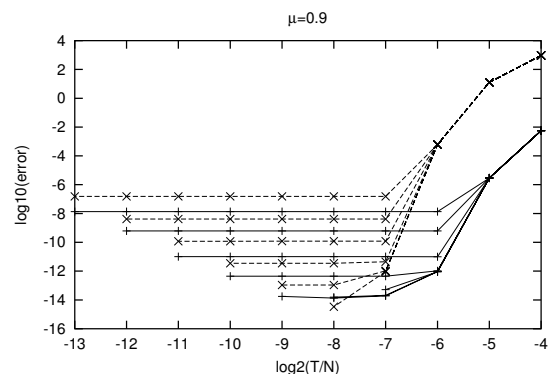
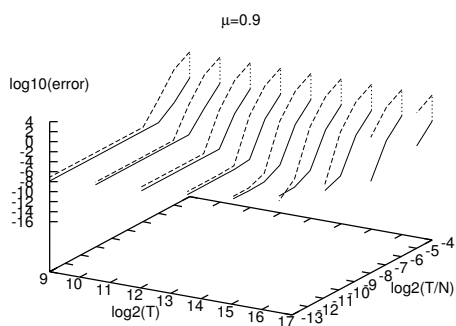
## Numerical test of the bounds obtained: actual error vs. predicted error

In the preceding slide, the difference between the **error predicted** and the **actual error** is big because of the **Diophantine condition**, which is reached for for **very few orders**  $|k|$ .

The points in the plot below represent  $\min_{|k|=\text{const.}} |k\omega|$  for  $|k| = 1 \div 1000$ . The curve represents the values of the Diophantine condition  $0.85355/|k|$ .



If we **substitute the first term of  $\|\Delta b\|$**  by what is obtained just **before the use of the Diophantine condition**, the following figure is obtained.



Solid line: actual error. Dashed line: estimated error.