



Centre de Visió
per Computador

Text Detection in Urban Scenes

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2009

Text detection

■ Applications:

- Security: plate control
- Social systems: Navigation and translation
- Etc.



■ Difficulties:

- Changes in appearance!



Layout

- Text detection
- Text features
- Learning text
- Results
- Conclusions

Text detection – Gradient features

Features for generalizing text structure????



ICDAR 2003 conference

OPERATING

T

OPERATING

$\frac{\partial T}{\partial y}$

OPERATING

$\frac{\partial T}{\partial x}$

OPERATING

$|\nabla T|$

$$|\nabla T| = \sqrt{\frac{\partial T}{\partial x}^2 - \frac{\partial T}{\partial y}^2}$$

$$\nabla T = \left(\frac{\partial T}{\partial x}, \frac{\partial T}{\partial y} \right)$$

Text detection – Celcius transform

$$\begin{array}{|c|c|c|} \hline 34 & 62 & 98 \\ \hline 34 & 62 & 98 \\ \hline 34 & 34 & 98 \\ \hline \end{array} \rightarrow \begin{matrix} 1 & 1 & 0 \\ 1 & 0 & \\ 1 & 1 & 0 \end{matrix} \rightarrow (11010110)_2 \rightarrow CT = 214$$

OPERATING

T

OPERATING

$\frac{\partial T}{\partial x}$

OPERATING

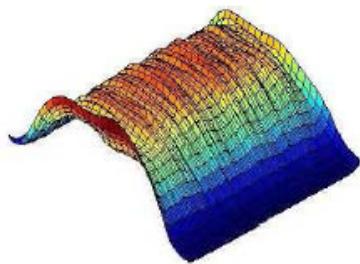
$|\nabla T|$

OPERATING

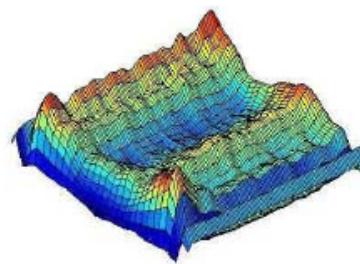
$\frac{\partial T}{\partial y}$

OPERATING

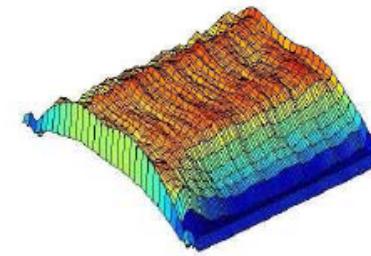
CT



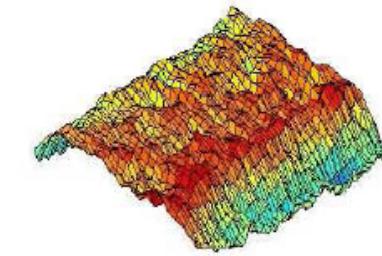
$|\frac{\partial T}{\partial x}|$



$|\frac{\partial T}{\partial y}|$



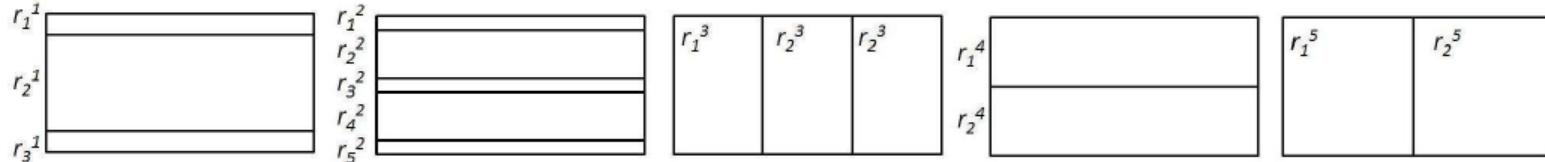
$|\nabla T|$



CT

ICDAR 2003 conference

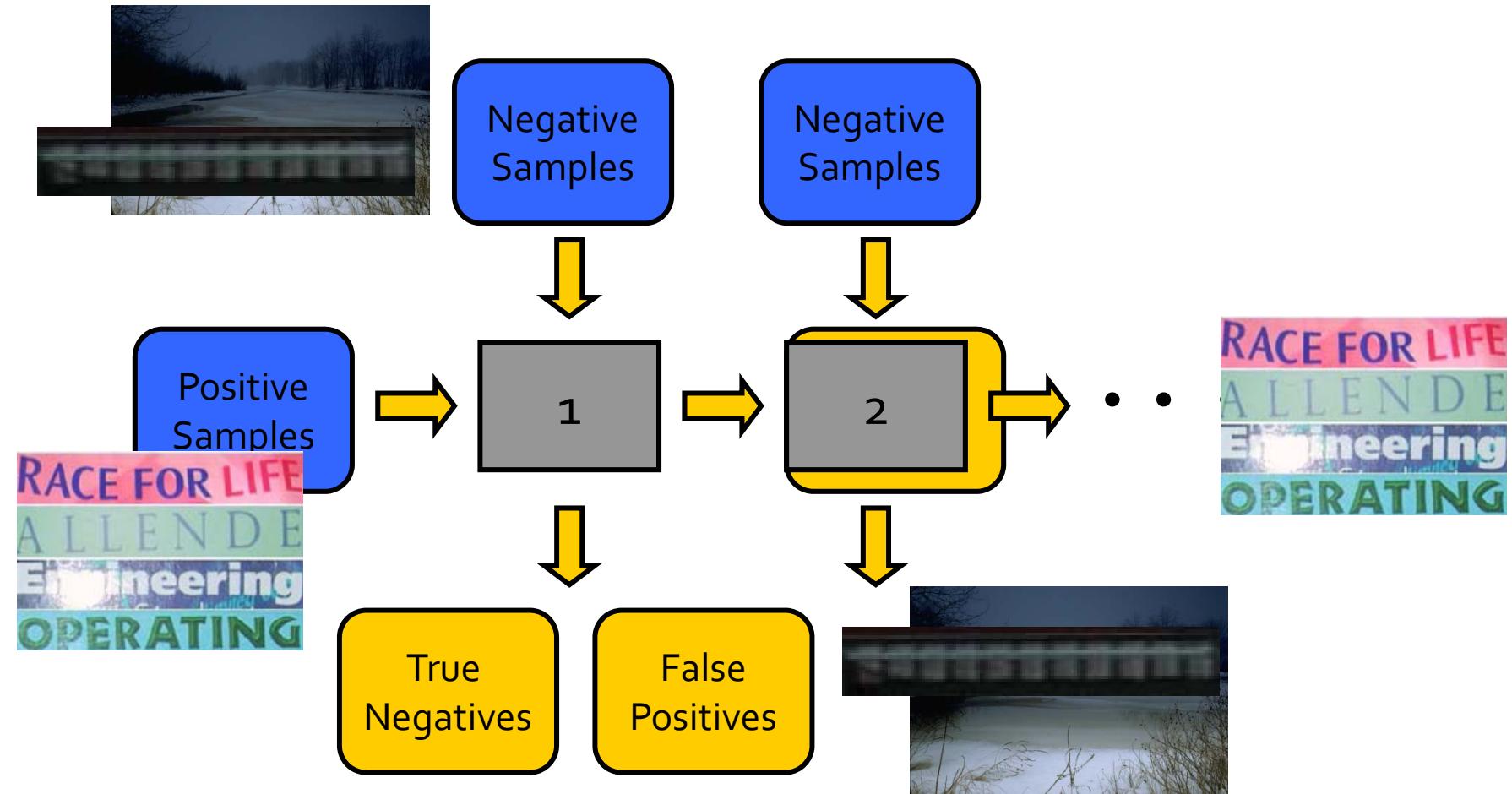
Text detection – Set of features



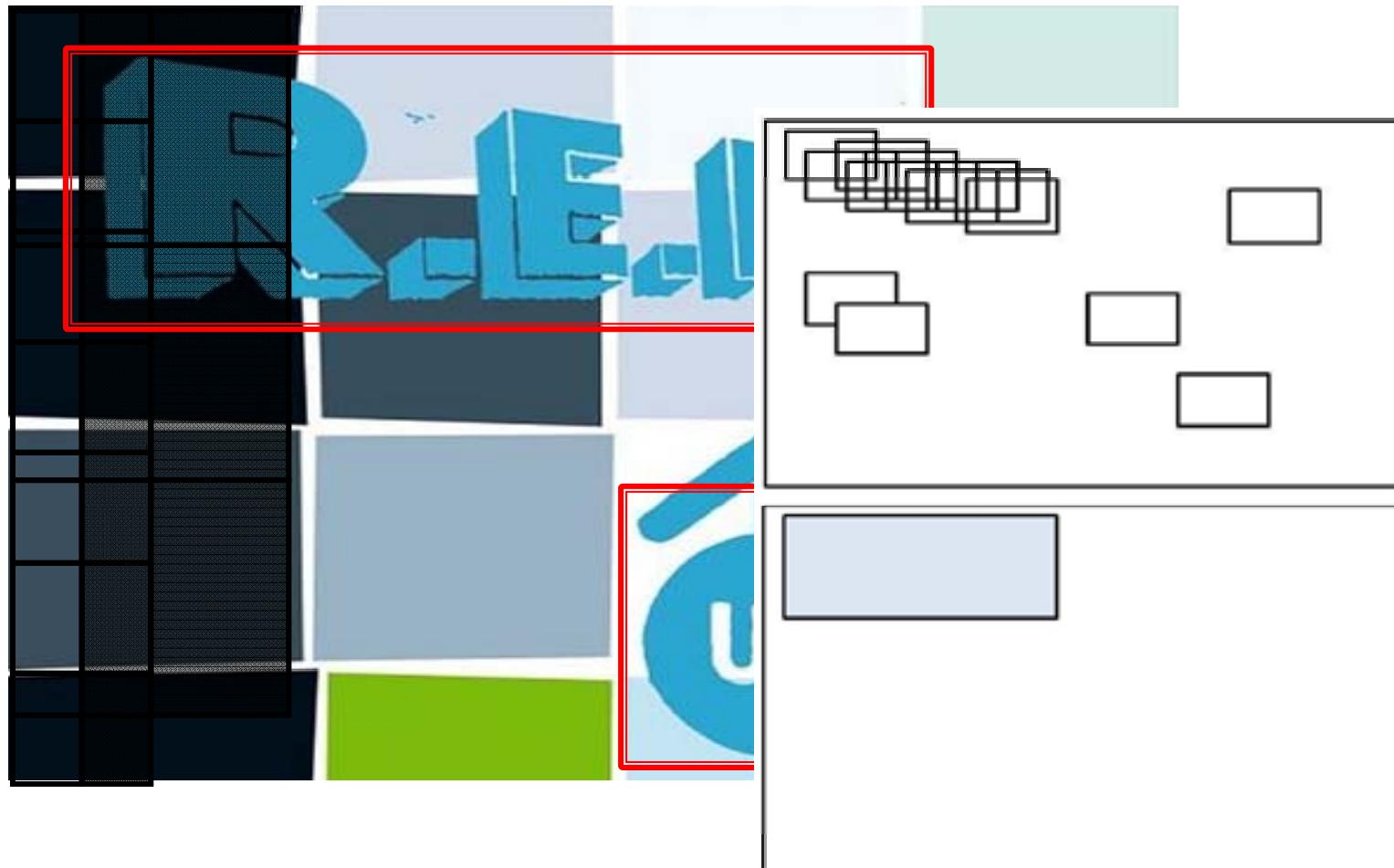
R_1	$\frac{\sum_k r_{2,k}^1 - \sum_k r_{1,k}^1}{\sum_k r_{2,k}^1 - (\sum_k r_{1,k}^1 + \sum_k r_{3,k}^1)}$	$r_1^1 : 1/6h \times 2h$ $r_2^1 : 2/3h \times 2h$ $r_3^1 : 1/6h \times 2h$
R_2	$\frac{\sum_k r_{2,k}^2 - (\sum_k r_{1,k}^2 + \sum_k r_{3,k}^2)}{\sum_k r_{2,k}^2 + \sum_k r_{4,k}^2 - (\sum_k r_{1,k}^2 + \sum_k r_{3,k}^2 + \sum_k r_{5,k}^2)}$	$r_1^2 : 1/9h \times 2h$ $r_2^2 : 1/3h \times 2h$ $r_3^2 : 1/9h \times 2h$ $r_4^2 : 1/3h \times 2h$ $r_5^2 : 1/9h \times 2h$
R_3	$\frac{\sum_k r_{2,k}^3 - \sum_k r_{1,k}^3}{\sum_k r_{2,k}^3 - (\sum_k r_{1,k}^3 + \sum_k r_{3,k}^3)}$	$r_1^3 : h \times 2/3h$ $r_2^3 : h \times 2/3h$ $r_3^3 : h \times 2/3h$
R_4	$\sum_k r_{2,k}^4 - \sum_k r_{1,k}^4$	$r_1^4 : h/2 \times 2h$ $r_2^4 : h/2 \times 2h$
R_5	$\sum_k r_{2,k}^5 - \sum_k r_{1,k}^5$	$r_1^5 : h \times h$ $r_2^5 : h \times h$

11 × 4 = 44 features per text region

Classifier Cascade - learning

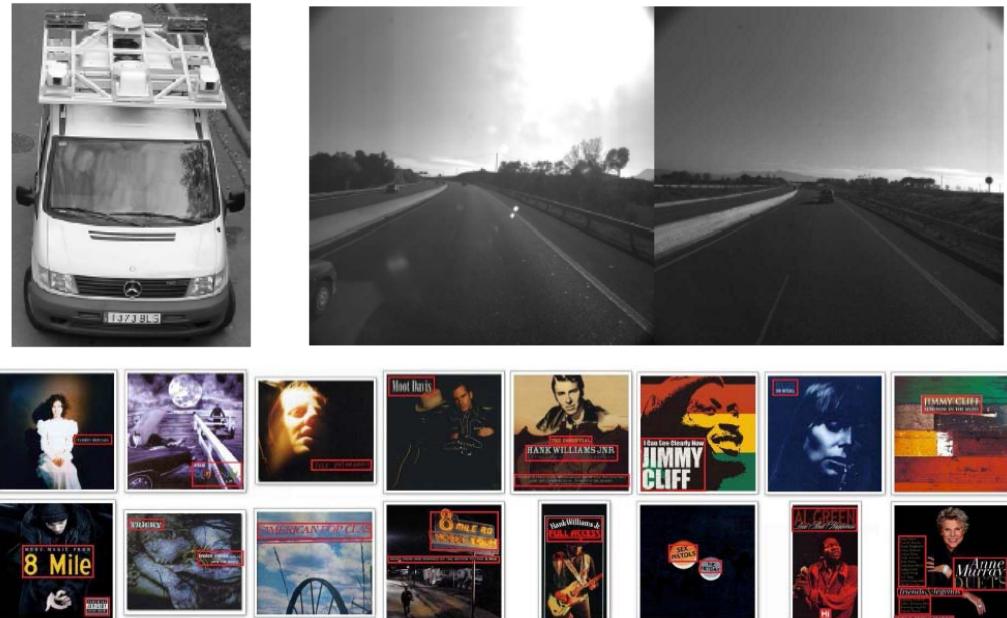


Classifier Cascade - testing



Text detection – Results

- **Data**
 - Mobile mapping system
 - Cover data set
- **Methods**
 - Gradient and CT features
 - Cascade of classifiers
 - Gentle Adaboost 50 decision stumps
- **Measurements**



$$A = \frac{\# \text{ Hits}}{\# \text{ Text regions in the analyzed frames}}$$

$$FR = \min \left(\frac{\# \text{ False positive detections}}{\# \text{ Analyzed frames}}, 1 \right)$$

$$\text{Performance} = \frac{\text{Detected text area} \cap \text{ground truth text area}}{\text{Detected text area} \cup \text{ground truth text area}}$$

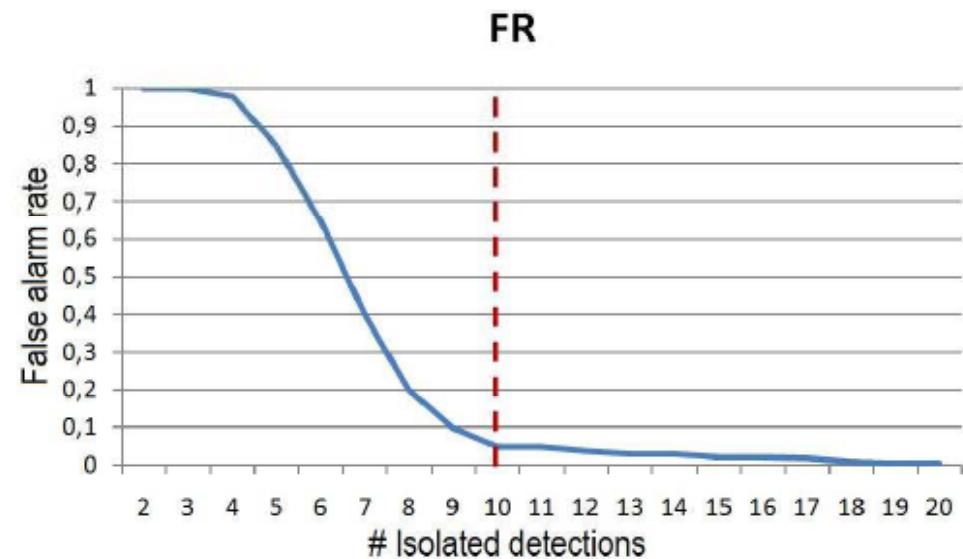
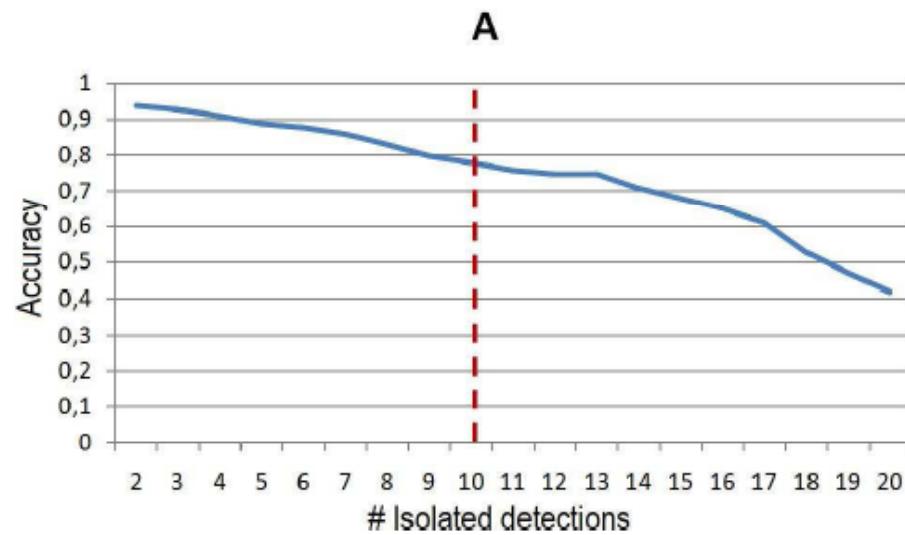
Text detection – Results

- Mobile Mapping – Highway sequences
- 2000 frames (20 km)
- A=0.89
- FR=0.02



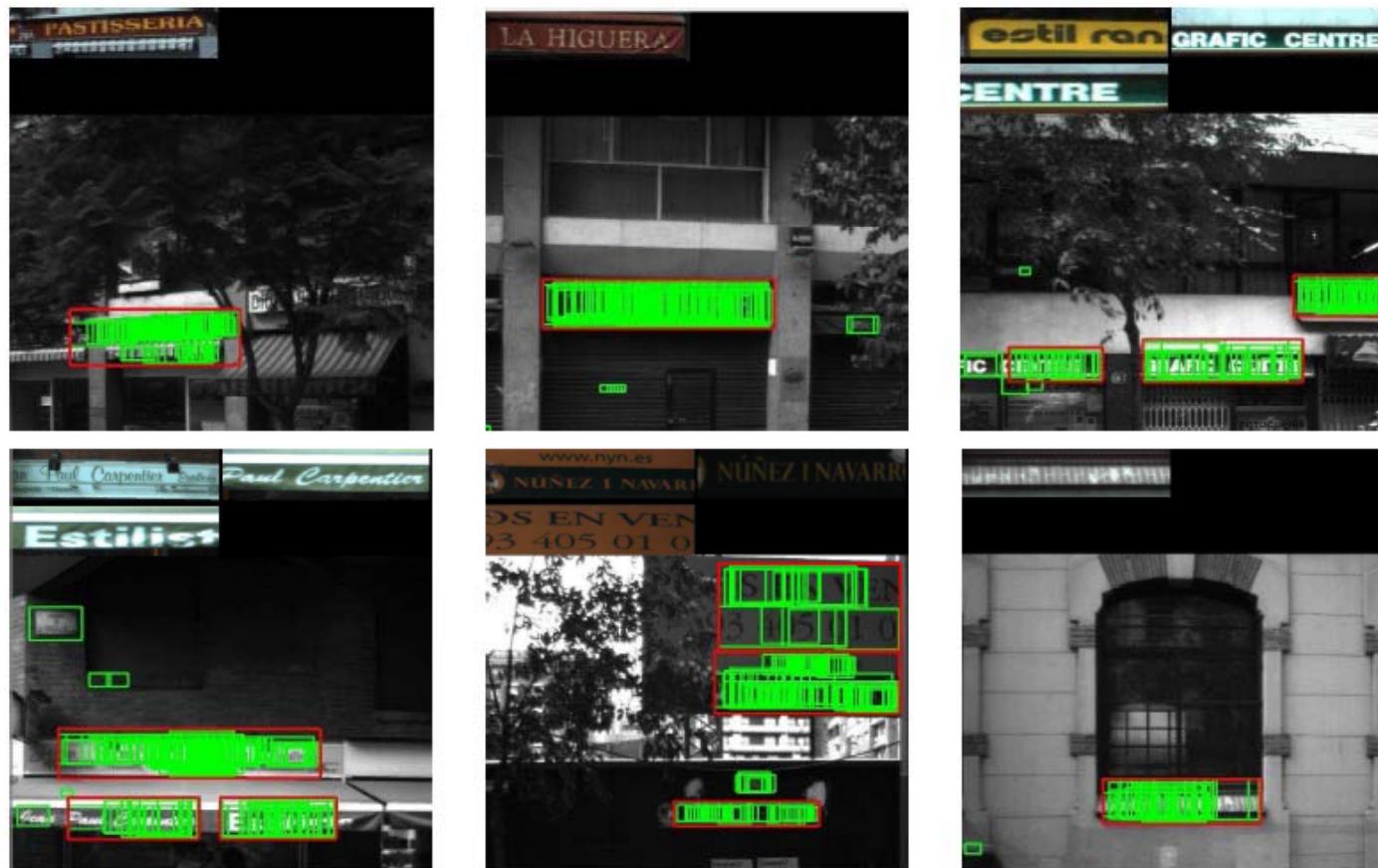
Text detection – Results

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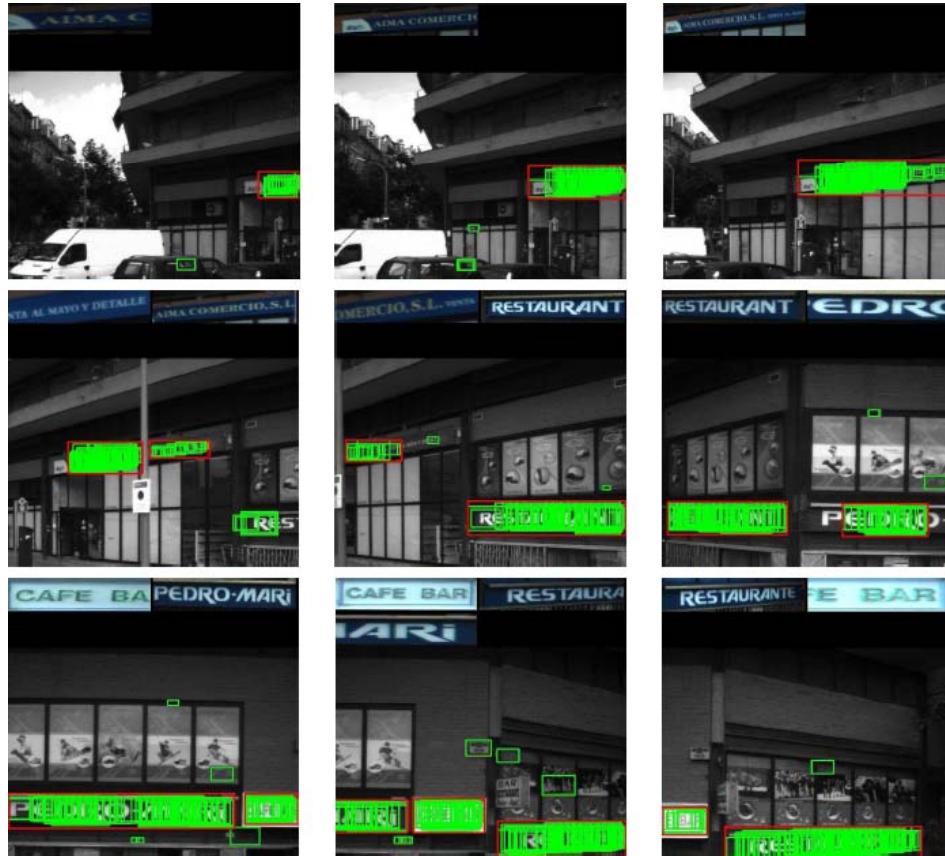
Text detection – Results

- Mobile Mapping – Urban sequences
- 2000 frames (8 km)
- A=0.78
- FR=0.29



Text detection – Results

■ Mobile Mapping – Urban sequences



Text detection – Cover data set

■ Mobile Mapping – Cover data set



$$Performance = \frac{\text{Detected text area} \cap \text{ground truth text area}}{\text{Detected text area} \cup \text{ground truth text area}}$$

1000 cover images tested:

Performance = 0.63

Text translation application in mobile platforms

**ACCURATE TEXT DETECTION
IN CLUTTER SCENES**

Conclusions

- Simple text features that allow high generalization of text structure
- Fast and accurate text detection over real data using a cascade of classifiers
- High performance over real data from a Mobile Mapping system and a new Cover data set
(<http://bcnpcl.uab.cat/>)
- Future work:
 - Analyze FP and FN and include proper complex features
 - Final levels of the cascade
 - Weighted by complexity



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Thank you!!

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